Can we trust $L_2$-criteria and $L_2$-losses?

**Titre:** Peut-on avoir confiance dans les critères et les fonctions de perte $L_2$?

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In this thorough survey, Sylvain Arlot adresses the important problem of estimator selection in Statistics. Given a $n$-sample $X = (X_1, \ldots, X_n)$ with distribution $P_r$ belonging to a parametrized statistical model $\mathcal{P} = \{P_r, s \in S\}$ and a loss function $\ell$ on $S^2$, the problem of estimator selection is that of finding from the data an estimator which minimizes the mapping $t \mapsto \ell(s^*, t)$ among a family $\{\hat{s}_m, m \in \mathcal{M}\} \subset S$ of candidate ones. The slope heuristics as well as other selection procedures aim at designing a selection rule, i.e. a mapping $X \mapsto \hat{m}(X)$ with values in $\mathcal{M}$, for which one can assure with a probability $p$ close to 1 that the selected estimator $\hat{s} = \hat{s}_m(X)$ satisfies an inequality of the form

$$\ell(s^*, \hat{s}) \leq K_n \inf_{m \in \mathcal{M}} \ell(s^*, \hat{s}_m) + R_n$$

where $K_n$ is a constant that we wish to be as close as possible to 1 and $R_n$ is an additional term that we wish to be as small as possible compared to $\inf_{m \in \mathcal{M}} \ell(s^*, \hat{s}_m)$. Inequality (1) is already interesting when the family $\{\hat{s}_m, m \in \mathcal{M}\}$ reduces to two distinct and deterministic points $\{s_0, s_1\} \subset S$ in which case the selection rule corresponds to a test between $s_0$ and $s_1$. When $s^*$ belongs to $\{s_0, s_1\}$ and the right-hand side of (1) is smaller than $\ell(s_0, s_1)$, this inequality tells us that the procedure selects the true parameter with a probability at least $p$. Our aim is to discuss the property of this test and the pieces of information that an inequality like (1) brings on the true distribution $P_r$ of the data.

When the parameter set $S$ is a subset of a Hilbert space $\mathcal{H} = L_2(\mu)$ for some suitable measure $\mu$, a convenient loss (from the point of view of the mathematical analysis) is that given by the Hilbert norm $||\cdot||$. I shall refer to $||\cdot||$ as a $L_2$-loss and more specifically focus on the following typical examples.

**Example 1** (The regression setting). We observe a random vector $X = (X_1, \ldots, X_n)$ with values in $(\mathbb{R}^d)^n$ and mean of the form $(s, \ldots, s)$ or equivalently a $n$-sample $X_1, \ldots, X_n$ with values in $\mathbb{R}^d$ and mean $s = (s_1, \ldots, s_d) \in S$ where $S$ is a subset of the Hilbert space $\mathcal{H} = \mathbb{R}^d$. The space $\mathcal{H}$ can also be seen as $L_2(\mu)$ for $\mu$ being the counting measure on $\{1, \ldots, d\}$. Given a subgaussian distribution $Q$ on $\mathbb{R}$ and $s \in S$, $P_r$ denotes here the distribution of the vector $X = s + \varepsilon \in \mathbb{R}^d$ with $\varepsilon \sim Q^{\otimes d}$. I shall refer to the Gaussian framework when $Q$ is Gaussian. In this regression setting, statisticians often base their selection rule on the least squares that I shall see as a $L_2$-criterion.

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and define for \( t \in \mathbb{R}^d \) by
\[
\hat{\gamma}_{1,n}(t) = -\frac{2}{n} \sum_{i=1}^{n} \left( \sum_{j=1}^{d} t_{i,j} X_{i,j} \right) + \|t\|^2 \quad \text{with} \quad \|t\|^2 = \sum_{j=1}^{d} t_{j}^2.
\]

More precisely, given \( s_0 \) and \( s_1 \) in \( S \), the test based on the least squares selects \( s_0 \) when \( \hat{\gamma}_{1,n}(s_0) < \hat{\gamma}_{1,n}(s_1) \) and \( s_1 \) when \( \hat{\gamma}_{1,n}(s_0) > \hat{\gamma}_{1,n}(s_1) \), the choice between \( s_0 \) and \( s_1 \) being unimportant in case of equality.

**Example 2** (Density estimation). The parameter set \( S \) is here a family of densities which are squared integrable with respect to some dominating measure \( \mu \) and for \( s \in S \), \( P_s = s \cdot \mu \). Taking \( \mathcal{H} = L_2(\mu) \) and using the well-known \( L_2 \)-criterion \( \hat{\gamma}_{2,n} \) defined for \( t \in L_2(\mu) \) by
\[
\hat{\gamma}_{2,n}(t) = -\frac{2}{n} \sum_{i=1}^{n} t(X_i) + \|t\|^2 \quad \text{with} \quad \|t\|^2 = \int t^2 d\mu,
\]
one may test \( s^* = s_0 \) versus \( s^* = s_1 \) in the same way as we did in Example 1 with \( \hat{\gamma}_{2,n} \) in place of \( \hat{\gamma}_{1,n} \).

The similarities between the \( L_2 \)-criteria (2) and (3) are striking and the common Hilbertian structure that underlines both frameworks allows additionally to use very similar mathematical technics for analyzing their properties. Although quite similar in their mathematical forms, there exist, from a more statistical point of view, major differences between these two criteria and their ways of testing between \( s_0 \) and \( s_1 \). First of all, unlike the least squares in the Gaussian framework, the \( L_2 \)-criterion in density estimation does not provide a reliable test in general. A very simple counter-example is the following one. Assume that one observes a \( n \)-sample \( X'_1, \ldots, X'_n \) with values in a very large interval \( [0, 2\sqrt{a}] \) for some parameter \( a \) satisfying \( \sqrt{a} > n = 100 \). For convenience, we change the unit of the data by considering the random variables \( X_i = X'_i/\sqrt{a} \) for all \( i \in \{1, \ldots, n\} \) and take as a reference measure \( \mu = \sqrt{a}\lambda \) where \( \lambda \) denotes the usual Lebesgue measure on \( \mathbb{R} \). By doing so, the rescaled data \( X'_i \) take their values in the interval \( [0, 2] \). We assume that their true density (with respect to \( \mu \)) is \( s^* = s_0 = \mathbb{I}_{[0,1/a]} + a^{-1/2}(1 - a^{-1/2}) \mathbb{I}_{[1/a, 1/a + 1]} \) (which means that the data actually lie in the smaller interval \( [0, 1 + 1/a] \)) and we introduce the candidate density \( s_1 = (4a)^{-1/2} \mathbb{I}_{[0,2]} \) which is supported on the interval \( [0, 2] \). Note that both densities are bounded by \( 1 \). With a probability at least \( (1 - 1/\sqrt{a})^n \geq 0.36 \), no observation falls into the interval \( [0, 1/a] \) hence
\[
\hat{\gamma}_{2,n}(s_0) = (1/\sqrt{a}) \left[ -2(1 - 1/\sqrt{a}) + 1 + (1 - 1/\sqrt{a})^2 \right] = 1/a^{3/2},
\]
while
\[
\hat{\gamma}_{2,n}(s_1) = (1/\sqrt{a}) \left[ -2/2 + 1/2 \right] = -1/(2\sqrt{a}) < \hat{\gamma}_{2,n}(s_0).
\]

This means that the \( L_2 \)-criterion \( \hat{\gamma}_{2,n} \) fails to select the true density \( s_0 \) among \( \{s_0, s_1\} \) even though the distribution \( \hat{P}_{s_0} \) is quite different from \( \hat{P}_{s_1} \). Using the classical likelihood ratio test between \( s_0 \) and \( s_1 \) and the fact that the Hellinger affinity between the distributions \( P_{s_0} \) and \( P_{s_1} \) is
\[
\rho(s_0, s_1) = \int \sqrt{\rho_{s_0 s_1}} d\mu = \left( \sqrt{2} \right)^{-1} (a^{-3/4} + \sqrt{1 - a^{-1/2}}) < 0.71,
\]
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of probability not larger than
\[
\mathbb{P}\left[ \prod_{i=1}^{n} s_1(X_i) \geq \prod_{i=1}^{n} s_0(X_i) \right] = \mathbb{P}\left[ \prod_{i=1}^{n} \frac{s_1(X_i)}{s_0(X_i)} \geq 1 \right] \leq \rho^n(s_0, s_1) < 0.71^n,
\]
which is smaller than 5% when \( n \geq 9 \) and becomes completely negligible when \( n \) passes 100. It is actually well-known that in density estimation the \( L_2 \)-criterion and the \( L_2 \)-loss suffer from many drawbacks and we refer the reader to Devroye and Lugosi (2001, Section 6.5) and Birgé (2014) for a related discussion.

This weakness of the \( L_2 \)-criterion completely disappears in the Gaussian framework since choosing there between the parameters \( s_0 \) and \( s_1 \) by means of the least squares is equivalent to using the likelihood ratio test between \( P_{s_0} \) and \( P_{s_1} \) (which is of course optimal). The good property of the least squares criterion actually extends to the subgaussian case and there is no need for \( s^* \) to be an element of \( \{ s_0, s_1 \} \) to make the correct choice since it can be proven that this criterion is likely to select the closest point to \( s^* \) (for the Euclidean distance) even in the case of a slight misspecification of this model.

However, the superiority of the \( L_2 \)-criterion in the Gaussian framework compared to the density one and our enthusiasm that may celebrate an inequality like (1) in the regression setting should be nuanced. The closeness of \( s^* \) and \( \hat{s} \) with respect to the Euclidean distance may say very little on the closeness of \( P_{s^*} \) and \( P_{\hat{s}} \). To see this, consider Example 1 with \( S = \mathbb{R}^d \), \( s^* = (1/2, \ldots, 1/2) \), \( Q \) the uniform distribution in \([-1/2, 1/2] \) (so that the coordinates of the \( X_i \) are uniformly distributed on \([0, 1] \)) and the problem of selecting between \( s_0 = s^* + (a, \ldots, a) \) and \( s_1 = s^* + (0, \ldots, 0, b) \) with \( a = 3/d \) and \( b = 10^{-1} \). I shall assume here that both the dimension \( d \) and the number \( n \) of observations are large, say larger than 15 000 for the sake of convenience. Then the parameter \( s_0 \) is much closer to the truth than \( s_1 \) since
\[
\| s^* - s_0 \|^2 = da^2 < 6.1 \times 10^{-4} < 10^{-2} = b^2 = \| s^* - s_1 \|^2,
\]
and applying Proposition 5 of Birgé (2006) (with \( X = (X_1, \ldots, X_n) \in \mathbb{R}^{nd} \), \( y = 4 \| s^* - s_0 \|^2 - \| s_0 - s_1 \|^2/4 \) and \( \varepsilon = 0 \)), we obtain that the least squares criterion selects \( s_0 \) (as expected) with a probability at least
\[
1 - \exp\left[-\frac{3n}{100} \left( \frac{\| s_0 - s_1 \|^2}{25} \right) \right] > 0.99.
\]
However, the distribution \( P_{s_0} \) is quite far away from the true one since
\[
\rho(P_{s^*}, P_{s_0}) = (1 - ad)^d < e^{-ad} = e^{-3} \quad \text{hence} \quad h^2(P_{s^*}, P_{s_0}) > 1 - e^{-3}
\]
while \( P_{s_1} \) satisfies \( h^2(P_{s^*}, P_{s_1}) = b = 10^{-4} \) and is therefore much closer! If the reader does not like the Hellinger distance, he can alternatively consider the total variation distance \( || \cdot ||_{\text{TV}} \) and check that
\[
\| P_{s^*} - P_{s_1} \|_{\text{TV}} = b = 0.01 \quad \text{while} \quad 1 \geq \| P_{s^*} - P_{s_0} \|_{\text{TV}} \geq 0.95.
\]
This discussion shows that the use of the \( L_2 \)-criterion (and the \( L_2 \)-distance) for estimating a density should be avoided in general and that, in the regression setting, an inequality like (1) (for the Euclidean loss) should be interpreted with caution. The closeness of the parameters does not translate in general to the closeness of the corresponding distributions, Comparing the behaviours of candidate estimators of \( s^* \) by comparing their Euclidean distances to it may lead to quite erroneous conclusions, at least when one is interested in the estimation of the true distribution of the data.
References

